

Two Clause Learning Approaches for Disjunctive Scheduling

Mohamed Siala, Christian Artigues, and Emmanuel Hebrard



Context

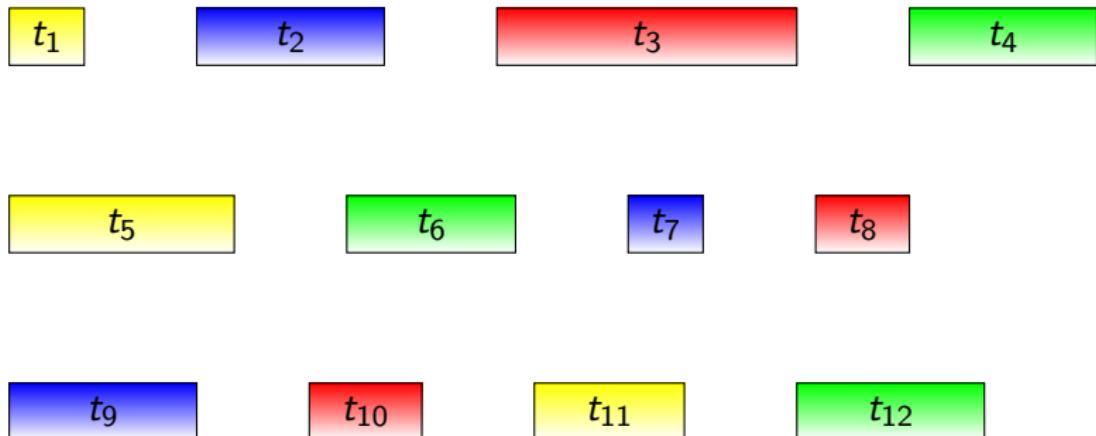
Disjunctive Scheduling

A family of scheduling problems having in common the Unary Resource Constraint.

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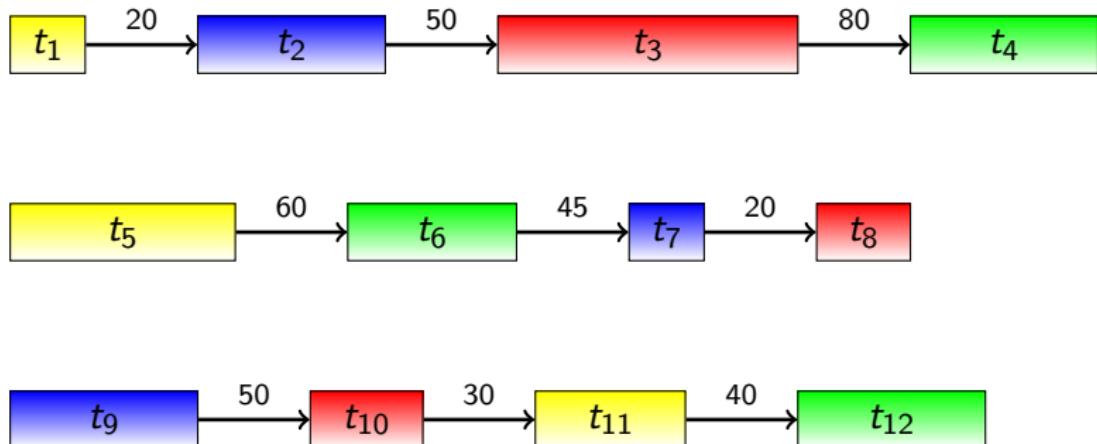
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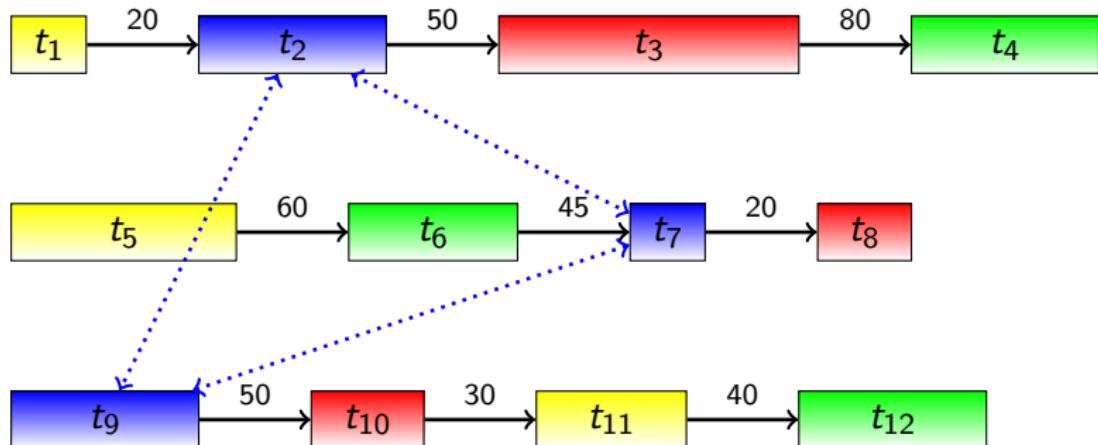
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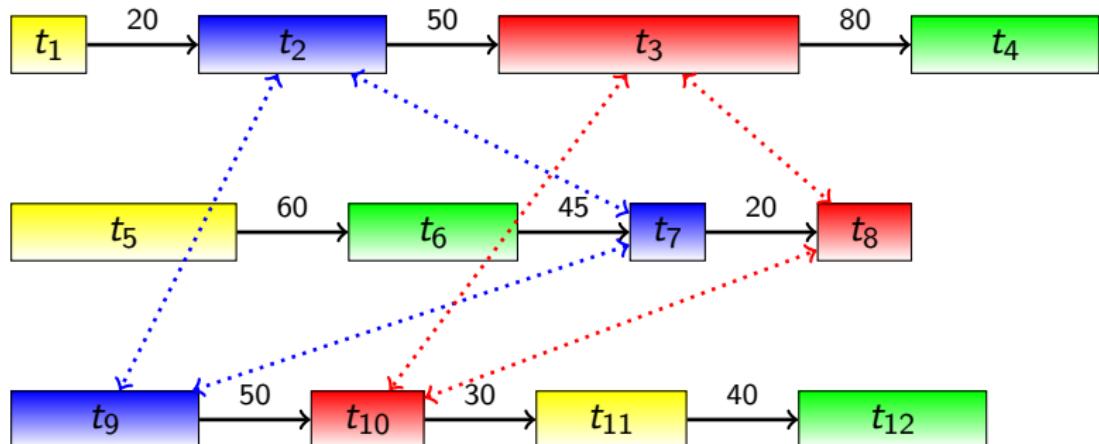
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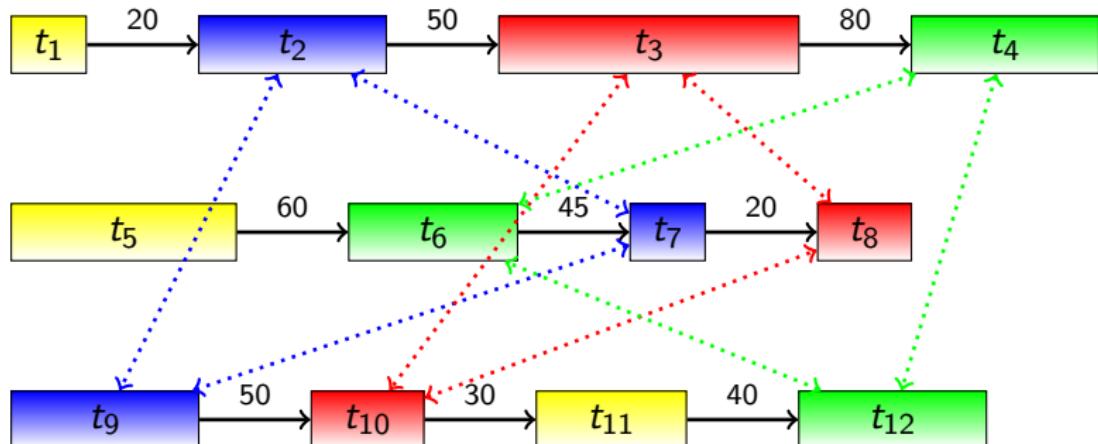
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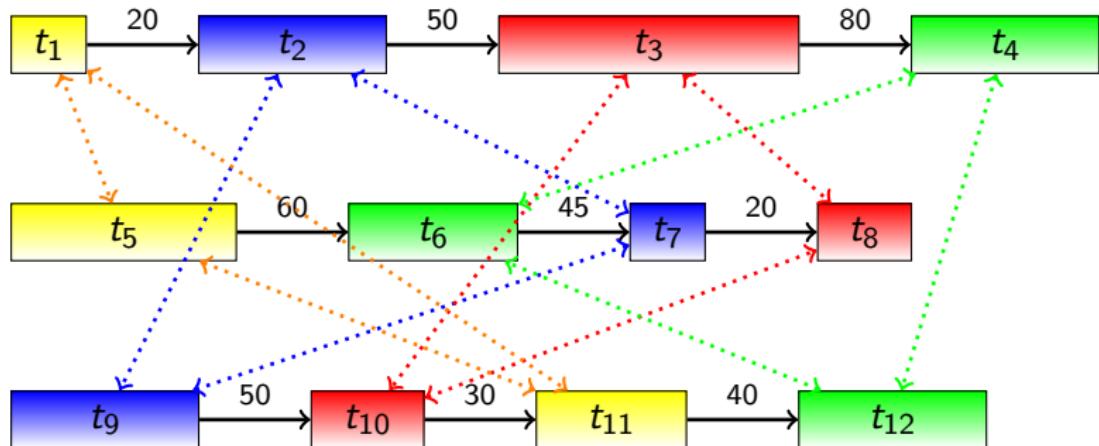
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Scheduling in CP

- Tradition
 - Tailored propagation algorithms (such as Edge-Finding [Carlier and Pinson, 1989])
 - Tailored search strategies (such as Texture [Sadeh, 1991]).

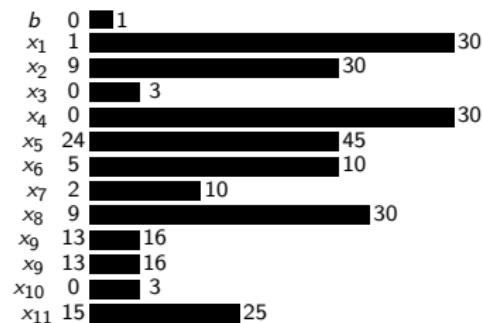
Context

Scheduling in CP

- Tradition
 - Tailored propagation algorithms (such as Edge-Finding [Carlier and Pinson, 1989])
 - Tailored search strategies (such as Texture [Sadeh, 1991]).
- New trend: Focus on what can be learnt during search
 - Lazy Clause Generation for RCPSP [Schutt et al., 2013].
 - Weight-based heuristic learning on disjunctive scheduling [Grimes and Hebrard, 2015].

Example

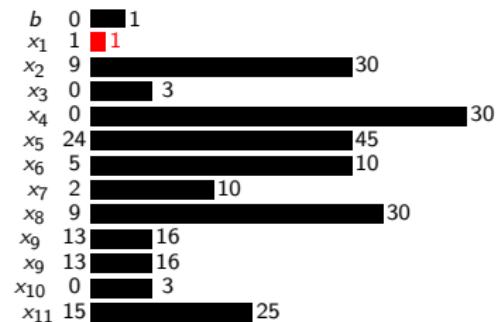
$$\begin{aligned}x_1 + x_7 &\geq 4 \wedge \\x_2 + x_{10} &\geq 11 \wedge \\x_3 + x_9 &= 16 \wedge \\x_5 &\geq x_8 + x_9 \wedge \\b \leftrightarrow (x_9 - x_4 &= 14) \wedge \\b \rightarrow (x_6 &\geq 7) \wedge \\b \rightarrow (x_6 + x_7 &\leq 9) \wedge \\x_{11} &\geq x_9 + x_{10}\end{aligned}$$



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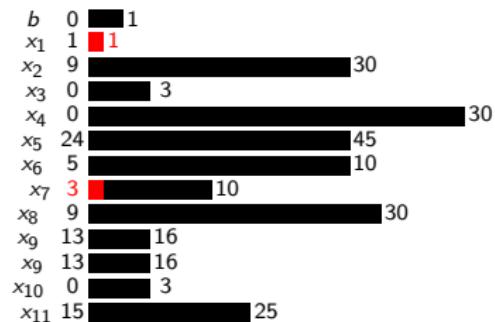
$\llbracket x_1 = 1 \rrbracket$



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$\llbracket x_1 = 1 \rrbracket \longrightarrow \llbracket x_7 \geq 3 \rrbracket$

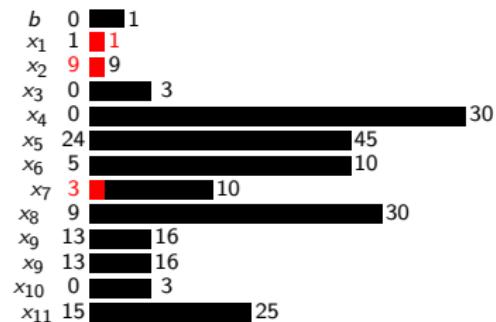


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$\llbracket x_1 = 1 \rrbracket \longrightarrow \llbracket x_7 \geq 3 \rrbracket$

$\llbracket x_2 = 9 \rrbracket$

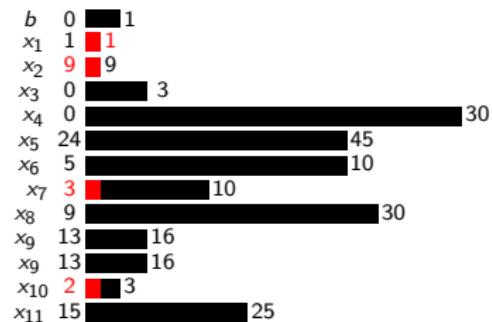


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$$[\![x_1 = 1]\!] \longrightarrow [\!x_7 \geq 3]\!]$$

$$[\!x_2 = 9]\!] \longrightarrow [\!x_{10} \geq 2]\!]$$



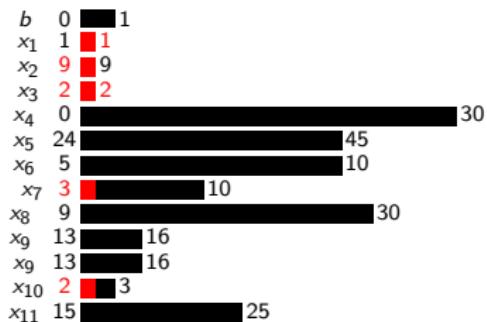
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$\llbracket x_1 = 1 \rrbracket \longrightarrow \llbracket x_7 \geq 3 \rrbracket$

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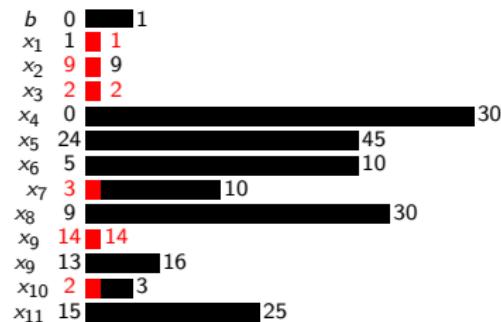
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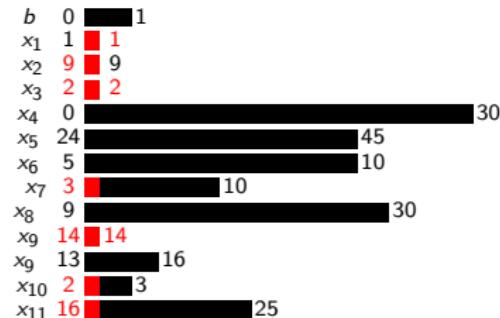
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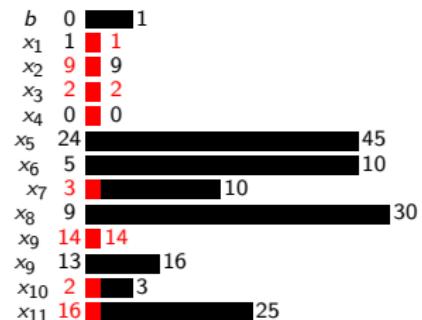
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b	1	1
x_1	1	1
x_2	9	9
x_3	2	2
x_4	0	0
x_5	24	45
x_6	5	10
x_7	3	10
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x_{10}	13	16
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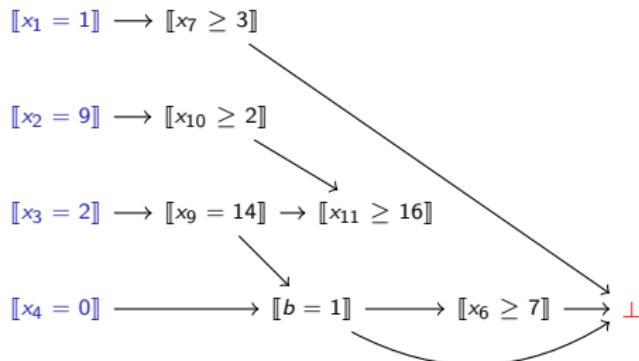
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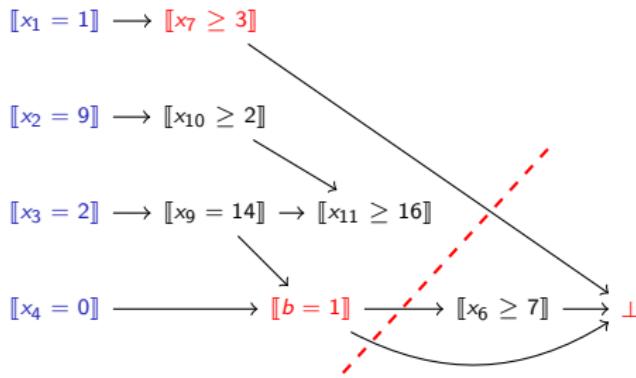
$$\llbracket x_4 = 0 \rrbracket \longrightarrow \llbracket b = 1 \rrbracket \xrightarrow{\quad} \llbracket x_6 \geq 7 \rrbracket \longrightarrow \perp$$

- Conflict analysis: $\llbracket b = 1 \rrbracket \wedge \llbracket x_7 \geq 3 \rrbracket \Rightarrow \perp$

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- Conflict analysis: $\llbracket b = 1 \rrbracket \wedge \llbracket x_7 \geq 3 \rrbracket \Rightarrow \perp$
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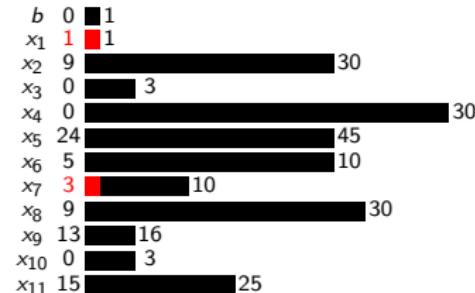
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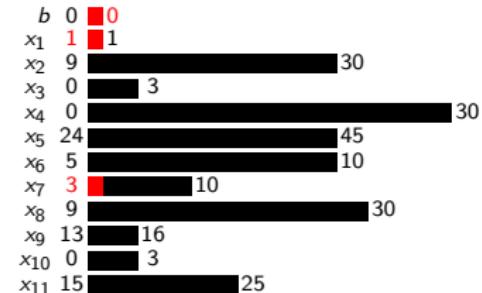


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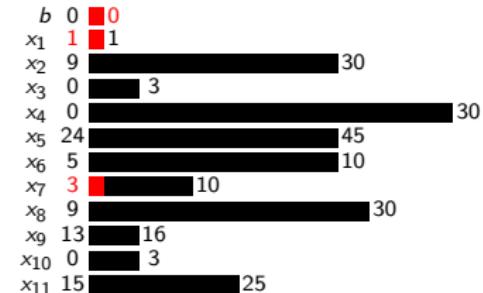


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- Backtrack to level 1
- Propagate the learnt clause
- Continue exploration

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Learning in CP

- Hybrid CP/SAT
- Conflict Driven Clause Learning (CDCL) [Moskewicz et al., 2001]
- Based on the notion of explanation
- Forward/Backward explanations
- Domain atoms can be generated Eagerly/Lazily

Our contributions

- Alternative lazy (atom) generation approach
- Novel conflict analysis scheme tailored to disjunctive scheduling

Modelling [Grimes and Hebrard, 2015]

Unary Resource Constraint

- $O(n^2)$ Boolean variables δ_{kij} ($i < j \in [1, n]$) per machine M_k .
- Decomposition using the following DISJUNCTIVE constraints:

$$\delta_{kij} = \begin{cases} 0 & \Leftrightarrow t_{ik} + p_{ik} \leq t_{jk} \\ 1 & \Leftrightarrow t_{jk} + p_{jk} \leq t_{ik} \end{cases} \quad (1)$$

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- Branch on the Boolean variables of the DISJUNCTIVE constraints.
- Variable ordering: wdeg, VSIDS.
- Value ordering: Solution guided [Beck, 2007].
- Greedy heuristic, dichotomic search, branch and bound

Revisiting Lazy Atom Generation

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Domain Encoding: standard approach

- ① Generate domain atoms: $a \leftrightarrow [x = d]$, $b \leftrightarrow [x \leq d]$
- ② Generate domain clauses: $\neg[x \leq d] \vee [x \leq d + 1]$,
 $\neg[x = d] \vee [x \leq d]$, etc

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Lazy Atom Generation

- ① Atoms and domain clauses are generated during conflict analysis
- ② There is a redundancy issue
- ③ Suppose that $[x \leq 2]$, $[x \leq 4]$ are already generated with
 $\neg[x \leq 2] \vee [x \leq 4]$ and we will generate $[x \leq 3]$.
- ④ Add $\neg[x \leq 2] \vee [x \leq 3]$, $\neg[x \leq 3] \vee [x \leq 4]$.
- ⑤ $\neg[x \leq 2] \vee [x \leq 4]$ is useless (redundant)
- ⑥ For a domain of size k , $k - 2$ redundant clauses.

Avoiding redundancy via DOMAINFAITHFULNESS

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Key Idea

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Arc consistency

Can be enforced in constant amortized time complexity ($O(1)$) down a branch of the search tree

DISJUNCTIVE-based Learning

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- Branch on the reified Boolean variables
- → There exists an explanation for every bound literal $\llbracket x \leq u \rrbracket$

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DISJUNCTIVE-based Learning

Two phases:

- ① 1-UIP cut
- ② Apply resolution for every bound literal until having a nogood with only reified Boolean variables

DISJUNCTIVE-based Learning

Example

- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$

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- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$
- $c \wedge [z \leq 13] \Rightarrow [x \leq 7]$

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- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$
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- Resolution $a \wedge \neg b \wedge c \wedge [z \leq 13] \wedge [y \leq 9] \Rightarrow \perp$
- $[x \geq 4] \Rightarrow [y \leq 9]$

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Example

- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$
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- $[x \geq 4] \Rightarrow [y \leq 9]$
- Resolution $a \wedge \neg b \wedge c \wedge [z \leq 13] \wedge [x \geq 4] \Rightarrow \perp$
- $a \wedge [x \geq 0] \Rightarrow [z \leq 13]$

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Example

- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$
- $c \wedge [z \leq 13] \Rightarrow [x \leq 7]$
- Resolution $a \wedge \neg b \wedge c \wedge [z \leq 13] \wedge [y \leq 9] \Rightarrow \perp$
- $[x \geq 4] \Rightarrow [y \leq 9]$
- Resolution $a \wedge \neg b \wedge c \wedge [z \leq 13] \wedge [x \geq 4] \Rightarrow \perp$
- $a \wedge [x \geq 0] \Rightarrow [z \leq 13]$
- Resolution $a \wedge \neg b \wedge c \wedge a \wedge [x \geq 0] \wedge [y \geq 4] \Rightarrow \perp$

DISJUNCTIVE-based Learning

Example

- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$
- $c \wedge [z \leq 13] \Rightarrow [x \leq 7]$
- Resolution $a \wedge \neg b \wedge c \wedge [z \leq 13] \wedge [y \leq 9] \Rightarrow \perp$
- $[x \geq 4] \Rightarrow [y \leq 9]$
- Resolution $a \wedge \neg b \wedge c \wedge [z \leq 13] \wedge [x \geq 4] \Rightarrow \perp$
- $a \wedge [x \geq 0] \Rightarrow [z \leq 13]$
- Resolution $a \wedge \neg b \wedge c \wedge a \wedge [x \geq 0] \wedge [y \geq 4] \Rightarrow \perp$
- Nogood Reduction $a \wedge \neg b \wedge c \wedge [y \geq 4] \Rightarrow \perp$

DISJUNCTIVE-based Learning

Example

- 1-UIP nogood: $a \wedge \neg b \wedge [x \leq 7] \wedge [y \leq 9] \Rightarrow \perp$
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- $\neg b \wedge [z \geq 0] \Rightarrow [y \geq 4]$

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- $\neg b \wedge [z \geq 0] \Rightarrow [y \geq 4]$
- Resolution $a \wedge \neg b \wedge c \Rightarrow \perp$

- ⊕ No domain encoding
- ⊕ Scheduling horizon does not matter in size
- ⊖ Language of literals is restricted compared to standard approaches

Experimental results

Protocol

- **Mistral-Hybrid:** backward explanations, semantic reductions, lazy generation, DISJUNCTIVE-based learning
- **<http://siala.github.io/jssp/details.pdf>**
- Lawrence and Taillard Job Shop benchmarks
- Global cutoff: 1h

Experimental results

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How hard are Taillard instances?

- Proposed 2 decades ago
- State-of-the art method recently proposed in [Vilím et al., 2015]
 - IBM CP-Optimizer studio
 - 8h20min per instance
 - Parallelization
 - Start search with best known bounds as an additional information.

Experimental results: Summary

Experimental results: Summary

Instances	CP(<i>task</i>)			H(<i>vsids, disj</i>)			H(<i>vsids, lazy</i>)			H(<i>task, disj</i>)			H(<i>task, lazy</i>)			
Mostly proven optimal																
la-01-40	87	522	8750	91.5	437	6814	88	632	2332	90.50	434	5218	88.75	509	2694	
tai-01-10	89	768	5875	90	517	4975	88	1060	1033	90	634	3572	84	1227	1013	
Hard instances																
tai-11-20	1.8432	4908	1.1564	3583	1.3725	531	1.2741	2544	1.2824	409	0.8745	409	3.8844	510	5.0136	390
tai-21-30	1.6131	3244	0.9150	2361	1.0841	438	0.9660	1694	1.2824	409	0.8745	409	3.8844	510	5.0136	390
tai-31-40	5.4149	3501	4.0210	2623	3.7350	580	4.0536	1497	1.2824	409	0.8745	409	3.8844	510	5.0136	390
tai-41-50	7.0439	2234	4.8362	1615	4.6800	436	4.9305	1003	1.2824	409	0.8745	409	3.8844	510	5.0136	390
tai-51-60	3.0346	1688	3.2449	2726	3.7809	593	1.1156	1099	1.1675	575	3.6617	533	1.1675	575	3.6617	533
tai-61-70	6.8598	1432	6.5890	2414	5.4264	578	3.9637	866	1.2824	409	0.8745	409	3.8844	510	5.0136	390

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Mostly proven optimal															
	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s
la-01-40	87	522	8750	91.5	437	6814	88	632	2332	90.50	434	5218	88.75	509	2694
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Hard instances															
	PRD	nd/s	PRD	nd/s	PRD	nd/s	PRD	nd/s	nd/s	PRD	nd/s	nd/s	PRD	nd/s	
tai-11-20	1.8432	4908	1.1564	3583	1.3725	531	1.2741	2544	1.2824	489					
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- Hybrid models outperform CP

Experimental results: Summary

Instances	CP(task)			H(vsids, disj)			H(vsids, lazy)			H(task, disj)			H(task, lazy)		
Mostly proven optimal															
la-01-40	%O	T	nds/s	%O	T	nds/s	%O	T	nds/s	%O	T	nds/s	%O	T	nds/s
la-01-40	87	522	8750	91.5	437	6814	88	632	2332	90.50	434	5218	88.75	509	2694
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Hard instances															
tai-11-20	PRD	nds/s	PRD	nds/s	PRD	nds/s	PRD	nds/s	PRD	nds/s	PRD	nds/s	PRD	nds/s	
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- The impact of clause learning is more visible when the size of the instance grows

Experimental results: Summary

Instances	CP(task)			H(vsids, disj)			H(vsids, lazy)			H(task, disj)			H(task, lazy)		
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tai-61-70	6.8598	1432	6.5890	2414	5.4264	578	3.9637	866	3.6617	533					

- DISJUNCTIVE-based learning outperforms the other models on medium sized instances

Experimental results: Summary

Instances	CP(task)			H(vsids, disj)			H(vsids, lazy)			H(task, disj)			H(task, lazy)		
Mostly proven optimal															
	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s
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- wdeg is the best choice with the largest instances.

Experimental results: Summary

Instances	CP(task)			H(vsids, disj)			H(vsids, lazy)			H(task, disj)			H(task, lazy)		
Mostly proven optimal															
	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s	%O	T	nd/s
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- Surprisingly DISJUNCTIVE-based learns shorter clauses

Experimental results: lower bounds computation

Experimental results: lower bounds computation

Open instances from Taillard benchmark before [Vilím et al., 2015]

- 7 new bounds found with DISJUNCTIVE-based learning and VSIDS

tai13		tai21		tai23		tai25		tai26		tai29		tai30	
new	old												
1305	1282	1613	1573	1514	1474	1544	1518	1561	1558	1576	1525	1515	1485

Experimental results: lower bounds computation

Open instances from Taillard benchmark before [Vilím et al., 2015]

- 7 new bounds found with DISJUNCTIVE-based learning and VSIDS

tai13		tai21		tai23		tai25		tai26		tai29		tai30	
new	old												
1305	1282	1613	1573	1514	1474	1544	1518	1561	1558	1576	1525	1515	1485
1342		1642		1518		1558		1591		1573		1519	

- 8h20min per instance
- Parallelization
- Start search with best known bounds as an additional information.

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Open instances from Taillard benchmark before [Vilím et al., 2015]

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tai13		tai21		tai23		tai25		tai26		tai29		tai30	
new	old												
1305	1282	1613	1573	1514	1474	1544	1518	1561	1558	1576	1525	1515	1485
1342		1642		1518		1558		1591		1573		1519	

- 8h20min per instance
- Parallelization
- Start search with best known bounds as an additional information.

Relaunch with 2h

- tai-29: 1583 (1573 in [Vilím et al., 2015])
- tai-30: 1528 (1519 in [Vilím et al., 2015])

Summary

- Alternative lazy (atom) generation approach avoiding a redundancy issue
- Novel conflict analysis mechanism
- Efficient in practice, specially for finding proofs

Future Research

- Applications to other scheduling problems?
- Learning with global constraints?
- Hand-crafted learning?

Thank you.

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