

# An optimal Arc Consistency algorithm for a Chain of Atmost Constraints with Cardinality

Mohamed Siala

The logo for LAAS-CNRS, featuring the text "LAAS-CNRS" in a blue, sans-serif font. The text is centered between two horizontal lines: a red line above and a yellow line below.

Toulouse, France

## Outline

Constraint Programming preliminaries

The ATMOSTSEQCARD constraint

Filtering the domains

Experimental results

Conclusion & Future work

## CSP

A constraint satisfaction problem (CSP) is a triplet  $P = (\mathcal{X}, \mathcal{D}, \mathcal{C})$  where

- $\mathcal{X}$  is a set of variables.
- $\mathcal{D}$  is the related sets of values.
- $\mathcal{C}$  is a set of constraints.

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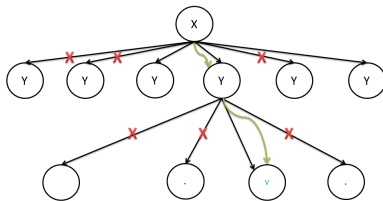
## Example

- $X = \langle x, y \rangle$
- $D = \langle \{1, 2, 3, 4\}, \{3, 4, 7, 10\} \rangle$
- $C_1 = \{x \text{ is even}\}$
- $C_2 = \{x + y \leq 7\}$
- **→A possible solution:**  $\langle x = 2, y = 4 \rangle$

# Propagation

- A propagator (or filtering algorithm) aims to remove some values that are inconsistent.
- **Correctness & Checking**

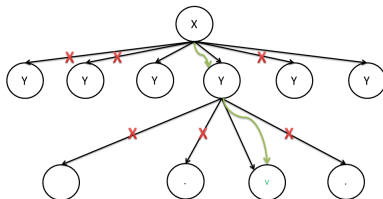
Figure: Propagation impact



# Propagation

- A propagator (or filtering algorithm) aims to remove some values that are inconsistent.
- **Correctness & Checking**

Figure: Propagation impact



- An arc consistency algorithm is a complete filtering algorithm, i.e. when associated to a constraint  $C$ , it removes all the inconsistent values.

## Global constraints

- A global constraint is constraint with unfixed arity ( $n > 2$ ).
- For instance, the AllDifferent( $x_1, x_2..x_n$ ) constraint ensures that the all variables,  $x_1$  to  $x_n$ , have different values.
- More than 360 constraints in the literature (see the global constraint catalog  
<http://www.emn.fr/z-info/sdemasse/gccat/>)
- A global constraint captures a sub-problem.
- A global constraint can be used to resolve different problems.
- A global constraint  $\leftrightarrow$  spatial propagator.

# Propagation & Global Constraints

## AllDifferent( $X, Y, Z$ )

$$X, Y, Z, D_X = D_Y = D_Z = \{1, 2\}$$

Decomposition	Global Constraint
$C_1 : X \neq Y; C_2 : Y \neq Z; C_3 : Z \neq X;$	AllDifferent( $X, Y, Z$ )
Propagate( $C_1$ ) : $C_1 : X \neq Y$ $D_X = D_Y \{1, 2\}$ → No propagation!	$D_X = D_Y = D_Z = \{1, 2\}$ → Failure!
Propagate( $C_2$ ), Propagate( $C_3$ ) : No propagation	



## Definition

$\text{ATMOSTSEQCARD}(u, q, d, [x_1, \dots, x_n]) \Leftrightarrow$

$$\bigwedge_{i=0}^{n-q} \left( \sum_{l=1}^q x_{i+l} \leq u \right) \wedge \left( \sum_{i=1}^n x_i = d \right)$$

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Example  $\text{ATMOSTSEQCARD}(2, 4, 4, [x_1, \dots, x_7])$

$\underline{0}$   $\underline{1}$   $\underline{1}$   $\underline{0}$   $\underline{1}$   $\underline{1}$   $0$   
 $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   
 $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$

$\underline{1}$   $\underline{1}$   $\underline{0}$   $\underline{0}$   $\underline{1}$   $\underline{0}$   $\underline{1}$   
 $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   
 $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$   $\underline{\quad}$

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- The AMONG constraint ensures that the number of occurrences of values in a given set of values  $v = \{v_1..v_k\}$  in a subsequence  $[x_{i_1}, \dots, x_{i_q}]$  is bounded between  $l$  and  $u$ .  
e.g.  $D(x_i) = \{0, \dots, 9\}$ ,  $v = \{3, 6\}$ ,  $l = 1$ ,  $u = 2$ ,  
*Among*  $([x_3, x_4, x_5, x_6], v, 1, 2)$  :

$[0,3,3,4]$  |  $[6,3,6,2]$

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- AMONGSEQ : the conjunction of all  $n - q + 1$  AMONG on  $q$  consecutive variables (i.e.  $\bigwedge_{i=0}^{n-q} \text{AMONG}([x_{i+1}, \dots, x_{i+q}])$ ).  
 e.g.  $AmongSeq([x_1, x_2, x_3, x_4, x_5, x_6], 4, v, l, u) \Leftrightarrow$   
 $Among([x_1, x_2, x_3, x_4], v, l, u) \wedge$   
 $Among([x_2, x_3, x_4, x_5], v, l, u) \wedge$   
 $Among([x_3, x_4, x_5, x_6], v, l, u)$ .

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- $ATMOSTSEQCARD \equiv AMONGSEQ \oplus$  a cardinality constraint
- $ATMOSTSEQCARD$  can be encoded with a GEN-SEQUENCE
- $ATMOSTSEQCARD$  can be encoded with a Global Sequencing Constraint (GSC)

## Existing complexities

### Gen-Sequence

- COST-REGULAR encoding:  $O(2^q n)$  [Van Hoesel et al, 2009]
- Gen-Sequence:  $O(n^3)$  [Van Hoesel et al, 2009]
- Flow-based Algorithm:  $O(n^2)$  [Maher et al, 2008]

### GSC

- GCC encoding, Not AC, NP-Hard [Puget and Régin, 1997]

# Why the ATMOSTSEQCARD constraint? [1]

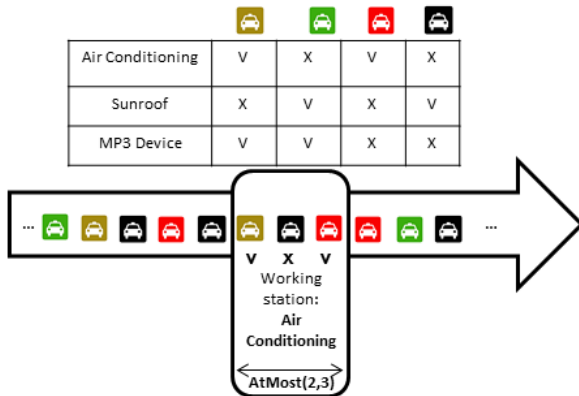


Figure: The car-sequencing problem

## Why the ATMOSTSEQCARD constraint? [2]

7 days, 4 employees, 3 periods, 40h per week, Atmost(1,3)

	D	E	N	D	E	N	D	E	N	D	E	N	D	E	N	D	E	N	d			
emp <sub>1</sub>	0	1	0	0	0	1	0	0	0	1	0	0	0	0	0	1	0	0	1	0	0	5
emp <sub>2</sub>	1	0	0	1	0	0	0	0	0	0	1	0	0	1	0	0	0	0	1	0	0	5
emp <sub>3</sub>	0	0	0	1	0	0	1	0	0	0	0	1	0	0	0	0	0	1	0	0	1	5
emp <sub>4</sub>	0	1	0	0	0	1	0	0	1	0	0	0	1	0	0	1	0	0	0	0	0	5

Table: Crew-rostering problem

## The proposed algorithm

- Let  $(x_1, \dots, x_n)$  be a boolean sequence subject to  $\text{ATMOSTSEQCARD}(u, q, d, [x_1, \dots, x_n])$
- Suppose that  $n = 50$ ,  $d = 17$ , and we have :  $D\{x_i\} = \{0, 1\}$ :
 

1	..	$i - 1$	$i$	$i + 1$	..	$n$
0	..	1	$D\{x_i\} = \{0, 1\}$	0	..	$\{0, 1\}$
- If  $\text{Max1Left}_{i-1} = 7$ ,  $\text{Max1Right}_{i+1} = 9$ ,  $\implies$  We have to force the variable  $x_i$  to have the value 1 in order to satisfy the cardinality.
- If  $\text{Max0Left}_{i-1} = 10$ ,  $\text{Max0Right}_{i+1} = 23$ ,  $\implies$  We have to force the variable  $x_i$  to have the value 0 in order to satisfy the occurrences of 0 (i.e.  $n - d = 33$ ).

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	1	2	<sup>c</sup> 3	4	$max$
.	0					
0	0					
.	0					
1	1					
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

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	$x_i$	$w$	1	2	<sup>c</sup> 3	4	<i>max</i>
→	.	—	0	0			
	0						
	.						
	1						
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	0						
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	1						
	.						
	.						
	1						
	.						
	.						



$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	$x_i$		$w$		$c$				
				1	2	3	4	$max$	
$\rightarrow$	.	—	0	<b>0</b>	<b>0</b>				
	0	—	0						
	.		0						
	1		1						
	.		0						
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	$x_i$		$w$		$c$		$max$
				1	2	3	4
→	.	—	0	<b>0</b>	<b>0</b>	<b>0</b>	
	0	—	0				
	.	—	0				
	1		1				
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	.		0				

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	$x_i$		$w$	$c$				$max$
				1	2	3	4	
$\rightarrow$	.	—	0	0	0	0	1	
	0	—	0					
	.	—	0					
	1	—	1					
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		1	2	3	4	
.	0	0	0	0	1	1
0	0					
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.	0					
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	$x_i$		$w$	$c$				$max$
				1	2	3	4	
	.	—	1	0	0	0	1	1
→	0	—	0	1				
	.		0					
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	$x_i$	$w$	$c$				$max$	
			1	2	3	4		
	.	—	1	0	0	0	1	1
→	0	—	0	1	1			
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	1		1					
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				1	2	3	4	
	.	—	1	0	0	0	1	1
→	0	—	0	1	1	2		
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				1	2	3	4	
	.		1	0	0	0	1	1
→	0	—	0	1	1	2	1	
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	1	—	1					
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$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0					
1	1					
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$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
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.	0					

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$x_i$		$w$	$c$				$max$
			1	2	3	4	
.	—	1	0	0	0	1	1
0	—	0	1	1	2	1	2
→ .	—	0	1				
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	$x_i$	$w$	$c$				$max$	
			1	2	3	4		
	.	—	1	0	0	0	1	1
	0	—	0	1	1	2	1	2
→	.	—	0	1	2			
	1	—	1					
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$x_i$		$w$	$c$				$max$
			1	2	3	4	
.		<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	—	0	1	1	2	1	2
→ .	—	0	1	2	1		
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$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
→ .	— 0	1	2	1	1	
1	— 1					
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		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
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		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1					
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$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	—	1	0	0	0	1
0	—	0	1	1	2	1
.	—	0	1	2	1	1
→ 1	—	1	2			
.		0				
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.		1	0	0	0	1	1
0	—	0	1	1	2	1	2
.	—	0	1	2	1	1	2
→ 1	—	1	2	1			
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			1	2	3	4	
.		1	0	0	0	1	1
0		0	1	1	2	1	2
.	—	0	1	2	1	1	2
→ 1	—	1	2	1	1		
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		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
→ 1	— 1	2	1	1	1	
.	— 0					
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		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	0					
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$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$		$w$	$c$				$max$
			1	2	3	4	
.		1	0	0	0	1	1
0	—	0	1	1	2	1	2
.	—	0	1	2	1	1	2
1	—	1	2	1	1	1	2
→ .	—	0	1				
.		0					
.		0					
0		0					
.		0					
0		0					
1		1					
.		0					
.		0					
1		1					
.		0					
.		0					



$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
→ .	0	1	1			
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
→ .	0	1	1	1		
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
→	—	0	1	1	1	0
.	—	0				
.	—	0				
0	—	0				
.	0					
0	0					
.	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	0	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	— 0	1	2	1	1	2
1	— 1	2	1	1	1	2
.	— 1	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
→ .	— 0	2				
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	—	1	2	1	1	2
.	—	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
→ .	—	0	2	2		
.	—	0				
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
→ .	<b>0</b>	2	2	1		
.	<b>0</b>					
0	<b>0</b>					
.	0					
0	0					
.	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					



$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
→ .	— 0	2	2	1	0	
.	— 0					
0	— 0					
.	— 0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0	2	2	1	0	2
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0	2	2	1	0	2
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0	2	2	1	0	2
.	0	2	1	0	0	2
0	0	1	0	0	1	1
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>	<b>1</b>
0	0	0	2	2	1	2
1	1	2	2	1	2	2
.	0	2	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0	2	2	1	0	2

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

$x_i$	$w$	$c$				$max$
		1	2	3	4	
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0	2	2	1	0	2
.	0	2	1	0	0	2
0	0	1	0	0	1	1
.	<b>1</b>	<b>0</b>	<b>0</b>	<b>1</b>	<b>1</b>	<b>1</b>
0	0	0	2	2	1	2
1	1	2	2	1	2	2
.	0	2	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	<b>1</b>	<b>1</b>	<b>1</b>	<b>1</b>	<b>0</b>	<b>1</b>
.	0	2	2	1	0	2

→ Complexity =  $O(n.q)$

## leftmost\_count

- `leftmost_count`( $[x_1, \dots, x_n], u, q, d$ ): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until  $i$ .

# leftmost\_count

- $\text{leftmost\_count}([x_1, \dots, x_n], u, q, d)$ : a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until  $i$ .
- Example:

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1		
<code>leftmost[i]</code>	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
<code>leftmost_count[i]</code>	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	7	8	8	9	10

# leftmost\_count

- `leftmost_count`( $[x_1, \dots, x_n], u, q, d$ ): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until  $i$ .
- Example:

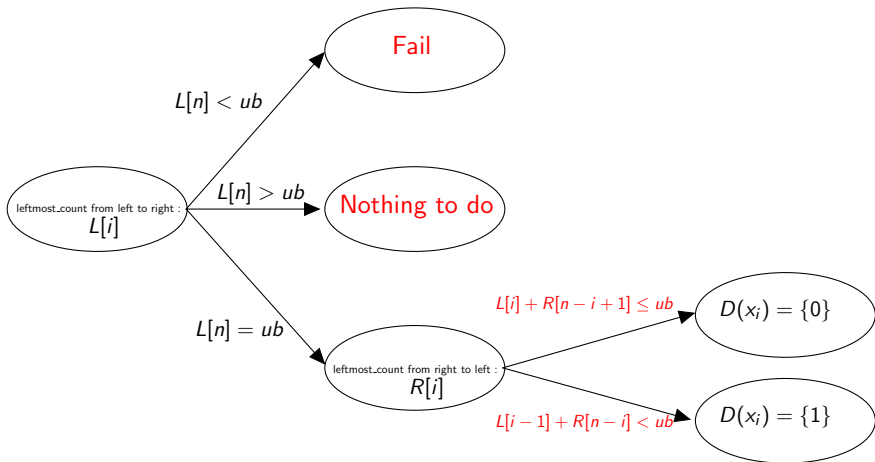
$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1	
<code>leftmost[i]</code>	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1
<code>leftmost_count[i]</code>	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10

- $L$  (resp.  $R$ ): the result of `leftmost_count` from left to right (resp. right to left).

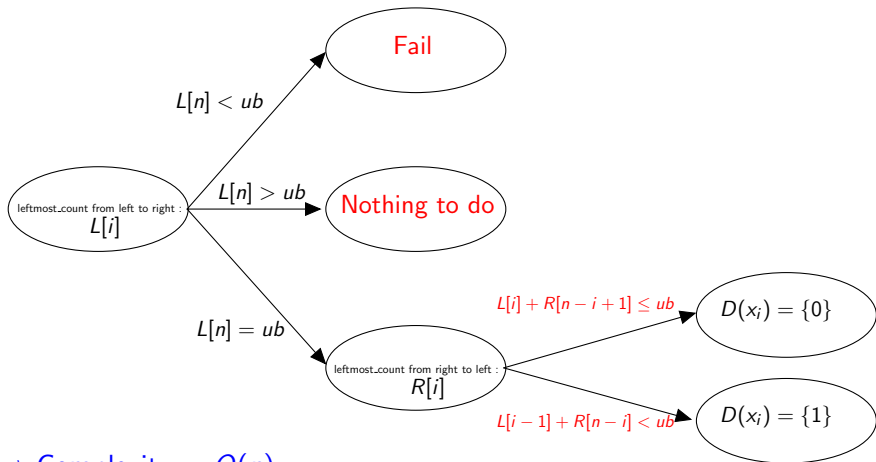


# The Arc consistency algorithm

# The Arc consistency algorithm



# The Arc consistency algorithm



→ Complexity =  $O(n)$

# $AC(u = 4, q = 8, d = 12, ub = 10)$

$\mathcal{D}(x_i)$       . 0 . . . . . 0 1 0 . . . . . 1

# $AC(u = 4, q = 8, d = 12, ub = 10)$

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1

# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1

# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[j]$	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10

# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[j]$	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0



# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	.	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[j]$	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	11	11	11	11	11	10	10

# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[j]$	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	11	11	11	11	11	10	10
$L[i - 1] + R[n - i]$	9	10	10	10	10	10	10	10	10	10	10	9	9	9	10	10	10	10	10	9	9	10	10

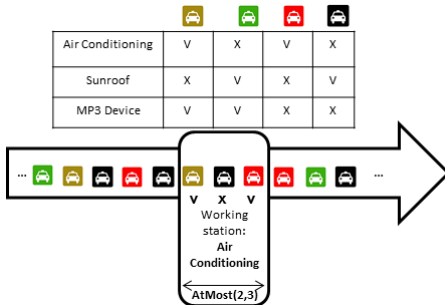
# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	.	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	10	11	11	11	11	10	10
$L[i - 1] + R[n - i]$	9	10	10	10	10	10	10	10	10	10	10	9	9	9	10	10	10	10	10	9	9	10	10
$AC(\mathcal{D}(x_i))$	1	0	.	.	.	.	0	0	0	1	0	1	1	1	0	0	0	.	.	1	1	1	

# AC( $u = 4, q = 8, d = 12, ub = 10$ )

$\mathcal{D}(x_i)$	.	0	.	.	.	.	.	.	0	1	0	.	.	.	.	.	.	.	.	.	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10	
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	11	11	11	11	10	10	
$L[i - 1] + R[n - i]$	9	10	10	10	10	10	10	10	10	10	10	9	9	9	10	10	10	10	10	9	9	10	
$AC(\mathcal{D}(x_i))$	1	0	.	.	.	.	0	0	0	1	0	1	1	1	0	0	0	.	.	1	1	1	

## Car-sequencing



### Constraints

- Each class  $c$  is associated with a demand  $D_c$ .
- For each option  $j$ , each sub-sequence of size  $q_j$  must contain at most  $u_j$  cars requiring the option  $j$ .

## Models

- 1 sum
- 2 gsc
- 3 amsc
- 4 amcs + gsc

## Heuristics

$\langle \{lex, mid\}, \{class, opt\}, \{1, q/u, d, \delta, n - \sigma, \rho\}, \{\leq_{\Sigma}, \leq_{Euc}, \leq_{lex}\} \rangle$ .  
→ 34 heuristics x 5 randomized tests.

## Benchmarks (CSP Lib)

- Groupe 1: 70 satisfiable instances
- Groupe 2: 4 satisfiable instances
- Groupe 3: 5 unsatisfiable instances
- Groupe 4: 7 satisfiable instances

# Experimental results

**Table:** Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
	#sol	time	#sol	time	#sol	time	#sol	time
sum	8480	13.93	95	76.60	0	> 1200	64	43.81
gsc	11218	3.60	325	110.99	31	276.06	140	56.61
amsc	10702	4.43	<b>360</b>	<b>72.00</b>	16	8.62	<b>153</b>	<b>33.56</b>
amsc+gsc	<b>11243</b>	<b>3.43</b>	339	106.53	<b>32</b>	<b>285.43</b>	147	66.45

## Experimental results

Table: Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
	#sol	time	#sol	time	#sol	time	#sol	time
sum	8480	13.93	95	76.60	0	> 1200	64	43.81
gsc	11218	3.60	325	110.99	31	276.06	140	56.61
amsc	10702	4.43	<b>360</b>	<b>72.00</b>	16	8.62	<b>153</b>	<b>33.56</b>
amsc+gsc	<b>11243</b>	<b>3.43</b>	339	106.53	<b>32</b>	<b>285.43</b>	147	66.45

- The level of filtering obtained by enforcing AC on the ATMOSTSEQCARD constraint is incomparable with that of the GCC encoding of the GSC constraint



## Experimental results

Table: Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
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- The level of filtering obtained by enforcing AC on the ATMOSTSEQCARD constraint is incomparable with that of the GCC encoding of the GSC constraint
- The GSC propagator seems to save more backtracks than ATMOSTSEQCARD.
- However, it's much slower than ATMOSTSEQCARD (overall a factor of **12.5** on the number of nodes explored per second!)

# Crew-rostering

	Week 1							W 2	W 3	W 4	d
emp <sub>1</sub>	---	---	---	---	---	---	---				17
emp <sub>2</sub>	---	---	---	---	---	---	---	..	..	..	17
..	---	---	---	---	---	---	---	..	..	..	17
emp <sub>20</sub>	---	---	---	---	---	---	---	..	..	..	17
demande:	6;6;3	6;6;3	6;6;3	6;6;3	6;6;3	2;2;1	2;2;1	..	..	..	17*20

## Constraints

- A required demand for each period.
- Each employee has to work 34 hours per week (17 shifts overall).
- Atmost 8h working shift per day.
- Atmost 5 days per week.

## Models

- *sum*
- *gsc*
- *amsc*

## Heuristics

- *worst employee*:  $MIN(\sigma_i = n_i - \frac{21d_i}{5}), MIN(\sigma'_j = m_j - d_j^s)$ .
- *worst shift*:  $MIN(\sigma'_j = m_j - d_j^s), MIN(\sigma_i = n_i - \frac{21d_i}{5})$

## Benchmarks

- 281 instances with different employee unavailabilities (ranging from from 18% to 46% by increment of 0.1).
- Set 1: 126 sat instances.
- Set 2: 111 instances (mostly sat).
- Set 3: 44 instances (mostly unsat).

## Experimental results

**Table:** Experimental results: Crew-Rostering

Benchmarks	G1 ( $5 \times 2 \times 126$ )		G2 ( $5 \times 2 \times 111$ )		G3 ( $5 \times 2 \times 44$ )	
	1260		1110		440	
	#sol	time	#sol	time	#sol	time
sum	1229	12.72	574	38.45	272	5.56
gsc	1210	29.19	579	77.78	276	24.14
amsc	<b>1237</b>	<b>5.82</b>	<b>670</b>	<b>31.01</b>	<b>284</b>	<b>6.22</b>

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- By analogy with the car-sequencing, there is one class with one option for each employee since we treat boolean variables.
- The GSC constraint here is equivalent to the ATMOSTSEQCARD hence can not do better than our propagator.
- ATMOSTSEQCARD is much faster than the GSC : a factor **20.4** in terms of explored nodes per second!



## Contributions

- Best existing complexity:  $O(n^2)$  [Maher et al, 2008].
- A complete filtering algorithm with a linear time complexity  $O(n)$ .
  - Car-sequencing
  - Crew-Rostering

## Future work

- Adapt the filtering rule with more general sequence constraints.
- Building a Propagator-based nogood generator for the ATMOSTSEQCARD algorithm in a Pseudo-Boolean Solver.

# Thank you!

## Questions?